

## Lecture 5

5.1

Recall:  $[X, Y] = -T \Rightarrow X, Y$  and their first-order commutators span  $\mathfrak{h}$ .  $\therefore X, Y$  alone determine  $\mathfrak{h}$ . They are known as the horizontal vector fields on  $\mathbb{H}^1$  and  $T$  is known as the "missing" direction.

Definition: The sub-Laplacian  $\mathcal{L}$  on  $\mathbb{H}^1$  is defined by

$$\mathcal{L} = -(X^2 + Y^2).$$

To see the sub-Laplacian more explicitly,

$$\begin{aligned} X^2 &= \left( \frac{\partial}{\partial x} + \frac{1}{2}y \frac{\partial}{\partial t} \right) \left( \frac{\partial}{\partial x} + \frac{1}{2}y \frac{\partial}{\partial t} \right) \\ &= \frac{\partial^2}{\partial x^2} + \frac{1}{2}y \frac{\partial^2}{\partial x \partial t} + \frac{1}{2}y \frac{\partial^2}{\partial t \partial x} + \frac{1}{4}y^2 \frac{\partial^2}{\partial t^2} \\ &= \frac{\partial^2}{\partial x^2} + y \frac{\partial^2}{\partial x \partial t} + \frac{1}{4}y^2 \frac{\partial^2}{\partial t^2}. \end{aligned}$$

$$\begin{aligned} Y^2 &= \left( \frac{\partial}{\partial y} - \frac{1}{2}x \frac{\partial}{\partial t} \right) \left( \frac{\partial}{\partial y} - \frac{1}{2}x \frac{\partial}{\partial t} \right) \\ &= \frac{\partial^2}{\partial y^2} - \frac{1}{2}x \frac{\partial^2}{\partial y \partial t} - \frac{1}{2}x \frac{\partial^2}{\partial t \partial y} + \frac{1}{4}x^2 \frac{\partial^2}{\partial t^2}. \end{aligned}$$

$$\begin{aligned} \therefore X^2 + Y^2 &= \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{1}{4}(x^2 + y^2) \frac{\partial^2}{\partial t^2} - \left( x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right) \frac{\partial}{\partial t}. \end{aligned}$$

$$\therefore \mathcal{L} = -\Delta - \frac{1}{4}(x^2 + y^2) \frac{\partial^2}{\partial t^2} + \left( x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right) \frac{\partial}{\partial t}.$$

Let  $\frac{\partial}{\partial z}$  and  $\frac{\partial}{\partial \bar{z}}$  be linear partial differential operators on  $\mathbb{R}^2$  given by

$$\begin{cases} \frac{\partial}{\partial z} = \frac{\partial}{\partial x} - i \frac{\partial}{\partial y}, \\ \frac{\partial}{\partial \bar{z}} = \frac{\partial}{\partial x} + i \frac{\partial}{\partial y}. \end{cases}$$

Then we define for  $\tau \in \mathbb{R} \setminus \{0\}$ , the linear partial differential operators  $Z_\tau$  and  $\bar{Z}_\tau$  by

$$\begin{cases} Z_\tau = \frac{\partial}{\partial z} + \frac{1}{2}\tau \bar{z}, & \bar{z} = x - iy, \\ \bar{Z}_\tau = \frac{\partial}{\partial \bar{z}} - \frac{1}{2}\tau z, & z = x + iy. \end{cases}$$

In fact,  $-\bar{Z}_\tau$  is the formal adjoint of  $Z_\tau$  in the sense that

$$(Z_\tau \varphi, \psi) = -(\varphi, \bar{Z}_\tau \psi)$$

for all Schwartz functions on  $\mathbb{H}^1$ . Let  $L_\tau$  be the linear partial differential operator on  $\mathbb{R}^2$  defined by

$$L_\tau = -\frac{1}{2} (Z_\tau \bar{Z}_\tau + \bar{Z}_\tau Z_\tau).$$

Let us write down  $L_z$  explicitly.

$$\begin{aligned} Z_\tau \bar{Z}_\tau &= \left( \frac{\partial}{\partial z} + \frac{1}{2} \tau \bar{z} \right) \left( \frac{\partial}{\partial \bar{z}} - \frac{1}{2} \tau z \right) \\ &= \Delta - \frac{1}{2} \tau z \frac{\partial}{\partial z} - \frac{1}{2} \tau + \frac{1}{2} \tau \bar{z} \frac{\partial}{\partial \bar{z}} - \frac{1}{4} \tau^2 |z|^2, \end{aligned}$$

and

$$\begin{aligned} \bar{Z}_\tau Z_\tau &= \left( \frac{\partial}{\partial \bar{z}} - \frac{1}{2} \tau z \right) \left( \frac{\partial}{\partial z} + \frac{1}{2} \tau \bar{z} \right) \\ &= \Delta + \frac{1}{2} \tau \bar{z} \frac{\partial}{\partial \bar{z}} + \frac{1}{2} \tau - \frac{1}{2} \tau z \frac{\partial}{\partial z} - \frac{1}{4} \tau^2 |z|^2. \end{aligned}$$

$$\begin{aligned} \therefore L_z &= -\frac{1}{2} (Z_\tau \bar{Z}_\tau + \bar{Z}_\tau Z_\tau) \\ &= -\frac{1}{2} \left( 2\Delta + \tau \bar{z} \frac{\partial}{\partial \bar{z}} - \tau z \frac{\partial}{\partial z} - \frac{1}{2} \tau^2 |z|^2 \right) \end{aligned}$$

Now,

$$\begin{aligned} \bar{z} \frac{\partial}{\partial \bar{z}} &= (x-iy) \left( \frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right) \\ &= x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + i \left( x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right), \end{aligned}$$

and

$$\begin{aligned} z \frac{\partial}{\partial z} &= (x+iy) \left( \frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right) \\ &= x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} - i \left( x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right) \end{aligned}$$

$$\therefore L_z = -\Delta + \frac{1}{4} (x^2 + y^2) - i \left( x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)$$

Hermite operator  
or simple harmonic  
oscillator

rotation or  
angular momentum operator