

## Lecture 4

4.1

Recall: Let  $\varepsilon = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} + c \frac{\partial}{\partial t} \in T_{(0,0,0)} \mathbb{H}^1$ , where

Then we get

$$V^\varepsilon = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} + \left( c + \frac{1}{2} ay - \frac{1}{2} bx \right) \frac{\partial}{\partial t}.$$

Now,  $V^\varepsilon \in \mathfrak{h}$ . Indeed, let  $(w, s) = (u, v, s) \in \mathbb{H}^1$ . Then

for all  $(z, t) = (x, y, t) \in \mathbb{H}^1$ ,  $f \in C^\infty(\mathbb{H}^1)$ ,

$$(V^\varepsilon L_{(w,s)} f)(z, t) = V^\varepsilon \left( f \left( \underbrace{u+x}_z, \underbrace{v+y}_y, \underbrace{s+t + \frac{1}{2}(vx-uy)}_t \right) \right)$$

$$= \left( a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} + \left( c + \frac{1}{2} ay - \frac{1}{2} bx \right) \frac{\partial}{\partial t} \right) (f(\dots))$$

$$= a \frac{\partial f}{\partial x}(\dots) + \frac{1}{2} av \frac{\partial f}{\partial t}(\dots) + b \frac{\partial f}{\partial y}(\dots) - \frac{1}{2} bu \frac{\partial f}{\partial t}(\dots)$$

$$+ \left( c + \frac{1}{2} ay - \frac{1}{2} bx \right) \frac{\partial f}{\partial t}(\dots)$$

$$= a \frac{\partial f}{\partial x}(\dots) + b \frac{\partial f}{\partial y}(\dots) + \left( c + \frac{1}{2} a(v+y) - \frac{1}{2} b(u+x) \right) \frac{\partial f}{\partial t}(\dots)$$

Next,

$$(L_{(w,s)} V^\varepsilon f)(z, t) = (V^\varepsilon f)(\dots)$$

$$= \left[ a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} + \left( c + \frac{1}{2} ay - \frac{1}{2} bx \right) \frac{\partial}{\partial t} \right] f(\dots)$$

$$= a \frac{\partial f}{\partial x}(\dots) + b \frac{\partial f}{\partial y}(\dots) + \left( c + \frac{1}{2} a(v+y) - \frac{1}{2} b(u+x) \right) \frac{\partial f}{\partial t}(\dots)$$

$$\therefore V^\varepsilon L_{(w,s)} = L_{(w,s)} V^\varepsilon \quad \therefore V^\varepsilon \in \mathfrak{h}.$$

It is obvious that

$$V^{\varepsilon_1} + V^{\varepsilon_2} = V^{\varepsilon_1 + \varepsilon_2}, \quad \varepsilon_1, \varepsilon_2 \in T_{(0,0,0)} \mathbb{H}^1,$$

and

$$\alpha V^{\varepsilon} = V^{\alpha \varepsilon}, \quad \alpha \in \mathbb{R}, \quad \varepsilon \in T_{(0,0,0)} \mathbb{H}^1.$$

$\therefore T_{(0,0,0)} \mathbb{H}^1$  and  $\mathfrak{h}$  are isomorphic vector spaces over  $\mathbb{R}$ .  $\therefore \mathfrak{h}$  is a three-dimensional real vector space. So,

we only need to prove that  $X, Y$  and  $T$  are linearly independent.

But for all  $a, b, c \in \mathbb{R}$  with  $aX + bY + cT = 0$ , let  $\rho$  be the

function on  $\mathbb{H}^1$  given by

$$\rho(x, y, t) = x, \quad (x, y, t) \in \mathbb{H}^1.$$

Then

$$((aX + bY + cT)\rho)(x, y, t) = 0$$

$$\Leftrightarrow \left( \left[ a \left( \frac{\partial}{\partial x} + \frac{1}{2} y \frac{\partial}{\partial t} \right) + b \left( \frac{\partial}{\partial y} - \frac{1}{2} x \frac{\partial}{\partial t} \right) + c \frac{\partial}{\partial t} \right] \rho \right)(x) = 0$$

$$\Leftrightarrow a = 0.$$

Similarly,  $b = 0$  and  $c = 0$ .  $\therefore \{X, Y, T\}$  is a basis for  $\mathfrak{h}$ .

The following theorem, which is an exercise tells us that

$X, Y$  and their first commutators span  $\mathfrak{h}$ . Hence we call

$\mathbb{H}'$  a step 1-Heisenberg group.

Theorem:  $[X, Y] = -T$  and all other commutators are zero.

Remarks:  $\{X, Y, T\}$  is a basis for  $\mathfrak{h}$ . So are many others.

Why is  $\{X, Y, T\}$  the preferred one?

Theorem: Let  $c_1, c_2$  and  $c_3$  be the coordinate axes in  $\mathbb{H}'$  and write them as

$$c_1(s) = (s, 0, 0),$$

$$c_2(s) = (0, s, 0),$$

and

$$c_3(s) = (0, 0, s)$$

for all  $s \in \mathbb{R}$ . Then for all  $C^\infty$  function on  $\mathbb{H}'$ ,  $(z, t) \in \mathbb{H}'$ ,

$$(Xf)(z, t) = \frac{d}{ds} \Big|_{s=0} f((z, t) \cdot c_1(s)),$$

$$(Yf)(z, t) = \frac{d}{ds} \Big|_{s=0} f((z, t) \cdot c_2(s)),$$

and

$$(Tf)(z, t) = \frac{d}{ds} \Big|_{s=0} f((z, t) \cdot c_3(s)).$$

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Proof: (X only) Let  $f \in C^\infty(\mathbb{H}^1)$ . Then for all  $(z, t) \in \mathbb{H}^1$ ,

$$(Xf)(z, t)$$

$$= \left. \frac{d}{ds} \right|_{s=0} f(z, t) \cdot c_1(s) = \left. \frac{d}{ds} \right|_{s=0} f((x, y, t) \cdot (s, 0, 0))$$

$$= \left. \frac{d}{ds} \right|_{s=0} f\left(x+s, y, t+\frac{1}{2}sy\right)$$

$$= \left( \frac{\partial f}{\partial x}(x+s, y, t+\frac{1}{2}sy) + \frac{\partial f}{\partial t}(x+s, y, t+\frac{1}{2}sy) \left(\frac{1}{2}y\right) \right) \Big|_{s=0}$$

$$= \frac{\partial f}{\partial x}(x, y, t) + \frac{1}{2}y \frac{\partial f}{\partial t}(x, y, t).$$

$$\therefore X = \frac{\partial}{\partial x} + \frac{1}{2}y \frac{\partial}{\partial t}.$$